## Product Preview <br> 5-Volt-Only Driver/Receiver With an Integrated Standby Mode

## EIA-232D and CCITT V. 28

The MC145705/06/07 are a series of silicon-gate CMOS transceiver ICs that fulfill the electrical specifications of EIA-232D and CCITT V. 28 while operating from a single +5 volt power supply. These transceiver series are high performance and low power consumption devices that are equipped with standby and output enable function.

A voltage doubler and inverter convert the +5 volts to $\pm 10$ volts. This is accomplished through an on-board 20 kHz oscillator and four inexpensive external electrolytic capacitors.

The MC145705 is composed of two drivers and three receivers, the MC145706 has three drivers and two receivers, and the MC145707 has three drivers and three receivers. These drivers and receivers are virtually identical to those of the MC145407.

Available Driver/Receiver Combinations

| Device | Drivers | Receivers | No. of Pins |
| :---: | :---: | :---: | :---: |
| MC145705 | 2 | 3 | 20 |
| MC145706 | 3 | 2 | 20 |
| MC145707 | 3 | 3 | 24 |

Drivers:

- $\pm 7.5$ Output Swing
- $300 \Omega$ Power-Off Impedance
- Output Current Limiting
- TTL and CMOS Compatible Inputs
- Three-State Outputs During Standby Mode
- Hold Output OFF (MARK) State by TxEN Pin


## Receivers:

- $\pm 25$ Volt Input Range
- 3 to $7 \mathrm{k} \Omega$ Input Impedance
- 0.8 V Hysteresis for Enhanced Noise Immunity
- Three-State Outputs During Standby Mode

Charge Pumps:

- +5 to $\pm 10$ V Dual Charge Pump Architecture
- Supply Outputs Capable of Driving Three Drivers on the MC145403/06 Simultaneously
- Requires Four Inexpensive Electrolytic Capacitors
- On-Chip 20 kHz Oscillators

MC145705
MC145706 MC145707


MC145705
2 Drivers/3 Receivers


MC145706
3 Drivers/2 Receivers


MC145707 3 Drivers/3 Receivers


FUNCTION DIAGRAM

## CHARGE PUMPS



RECEIVER


DRIVER


MAXIMUM RATINGS (Voltage Polarities Referenced to GND)

| Rating | Symbol | Value | Unit |
| :---: | :---: | :---: | :---: |
| DC Supply Voltage | $V_{C C}$ | -0.5 to +6.0 | V |
| Input Voltage <br> Rx1-3 Inputs DI1-3 Inputs | VIR | $\begin{gathered} \mathrm{V}_{\mathrm{SS}^{-15}} \text { to } \mathrm{V}_{\mathrm{DD}}+15 \\ -0.5 \text { to } \mathrm{V}_{\mathrm{CC}}+0.5 \end{gathered}$ | V |
| DC Current Per Pin | 1 | $\pm 100$ | mA |
| Power Dissipation | PD | 1 | W |
| Operating Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | -40 to +85 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $\mathrm{T}_{\text {stg }}$ | -85 to +150 | ${ }^{\circ} \mathrm{C}$ |

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, it is recommended that the voltage at the DI and DO pins be constrained to the range $G N D \leq V_{D I} \leq V_{D D}$ and $G N D$ $\leq \mathrm{V}_{\mathrm{DO}} \leq \mathrm{V}_{\mathrm{CC}}$. Also, the voltage at the Rx pin should be constrained to (VSS-15V) $\leq \mathrm{V}_{\mathrm{Rx} 1-3} \leq\left(\mathrm{V}_{\mathrm{DD}}+15 \mathrm{~V}\right)$, and Tx should be constrained to $\mathrm{V}_{\mathrm{SS}} \leq \mathrm{V}_{\mathrm{Tx} 1-3} \leq \mathrm{V}_{\mathrm{DD}}$.

Unused inputs must always be tied
to an appropriate logic voltage level
(e.g., GND or $\mathrm{V}_{\mathrm{CC}}$ for DI , and GND for
$R x$ ).

## RECOMMENDED OPERATING LIMITS

| Parameter | Symbol | Min | Typ | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Power Supply | $\mathrm{V}_{\mathrm{CC}}$ | 4.5 | 5 | 5.5 | V |
| Operating Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | -40 | - | 85 | ${ }^{\circ} \mathrm{C}$ |

DC ELECTRICAL CHARACTERISTICS (Voltage polarities referenced to GND $=0 \mathrm{~V} ; \mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3, \mathrm{C} 4=10 \mu \mathrm{~F}$; $\mathrm{T} \mathrm{A}=-40$ to $+85^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DC Power Supply | $\mathrm{V}_{\mathrm{CC}}$ | 4.5 | 5 | 5.5 | V |
| Quiescent Supply Current (Output Unloaded, Input Low) | ICC | - | 1.7 | 3.5 | mA |
| Quiescent Supply Current (Stand-By Mode) (Output Unloaded, Input Open) | $\mathrm{ICC}(\mathrm{STB})$ | - | <10 | 20 | $\mu \mathrm{A}$ |
| Control Signal Input Voltage (STB, TxEN) $\begin{gathered}\text { Logic Low } \\ \text { Logic High }\end{gathered}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{IL}} \\ & \mathrm{~V}_{\mathrm{IH}} \\ & \hline \end{aligned}$ | $\mathrm{V}_{\mathrm{CC}}-0.5$ | - | $0.5$ | V |
| Control Signal Input Current $\begin{array}{r}\text { Logic Low (TxEN) } \\ \text { Logic High (STB) }\end{array}$ | $\begin{aligned} & \mathrm{I}_{\mathrm{IL}} \\ & \mathrm{I}_{\mathrm{H}} \end{aligned}$ | $-$ | - | $\begin{gathered} -10 \\ 10 \end{gathered}$ | $\mu \mathrm{A}$ |
| Charge Pumps Output Voltage (C1, C2, C3, C4 $=10 \mu \mathrm{~F}$ ) Output Voltage (VDD) $\begin{array}{r} \text { Ioad }=0 \mathrm{~mA} \\ \text { I load }=5 \mathrm{~mA} \\ \text { I load }=10 \mathrm{~mA} \end{array}$ | $V_{D D}$ | $\begin{aligned} & 8.5 \\ & 7.5 \\ & 6.0 \\ & \hline \end{aligned}$ | $\begin{gathered} 10.0 \\ 9.5 \\ 9.0 \\ \hline \end{gathered}$ | $\frac{11}{-}$ | v |
| Output Voltage (VSS) $\begin{aligned} l_{\text {load }} & =0 \mathrm{~mA} \\ l_{\text {load }} & =5 \mathrm{~mA} \\ l_{\text {load }} & =10 \mathrm{~mA} \end{aligned}$ | $\mathrm{v}_{S S}$ | $\begin{aligned} & \hline-8.5 \\ & -7.5 \\ & -6.0 \end{aligned}$ | $\begin{gathered} \hline-10.0 \\ -9.2 \\ -8.6 \end{gathered}$ | $\begin{gathered} -11 \\ - \end{gathered}$ |  |

## RECEIVER ELECTRICAL SPECIFICATIONS

(Voltage polarities referenced to $\mathrm{GND}=0 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}}=+5 \mathrm{~V} \pm 10 \% ; \mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3, \mathrm{C} 4=10 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=-40$ to $+85^{\circ} \mathrm{C}$ )

| Parameter |  | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input Turn-On Threshold ( $\mathrm{VDO}^{1-3}=\mathrm{V}_{\mathrm{OL}}$ ) | Rx1-3 | $\mathrm{V}_{\text {on }}$ | 1.35 | 1.8 | 2.35 | V |
| Input Turn-Off Threshold ( $\mathrm{VDO}^{1-3}=\mathrm{V}_{\mathrm{OH}}$ ) | Rx1-3 | $V_{\text {Off }}$ | 0.75 | 1 | 1.25 | V |
| Input Threshold Hysteresis ( $\mathrm{V}_{\text {On }}=\mathrm{V}_{\text {off }}$ ) | Rx1-3 | $V$ hys | 0.6 | 0.8 | - | V |
| Input Resistance |  | $\mathrm{R}_{\text {in }}$ | 3 | 5.4 | 7 | $\mathrm{k} \Omega$ |
| High-Level Output Voltage (DO1-3) $V_{R x} 1-3=-3 \text { to }-25 \mathrm{~V}$ | $\begin{aligned} & I_{\text {out }}=-20 \mu \mathrm{~A} \\ & \mathrm{I}_{\text {out }}=-1 \mathrm{~mA} \end{aligned}$ | $\mathrm{V}_{\mathrm{OH}}$ | $\begin{aligned} & V_{C C}-0.1 \\ & V_{C C}-0.7 \end{aligned}$ | $\overline{4.3}$ | - | V |
| Low-Level Output Voltage (DO1-3) $V_{R x} 1-3=+3 \text { to }+25 \mathrm{~V}$ | $\begin{aligned} & \mathrm{I}_{\text {out }}=+20 \mu \mathrm{~A} \\ & \mathrm{I}_{\text {out }}=+1.6 \mathrm{~mA} \end{aligned}$ | VOL | - | $\begin{gathered} 0.01 \\ 0.5 \end{gathered}$ | $\begin{aligned} & 0.1 \\ & 0.7 \end{aligned}$ | V |

DRIVER ELECTRICAL SPECIFICATIONS
(Voltage polarities referenced to $\mathrm{GND}=0 \mathrm{~V} ; \mathrm{V} C \mathrm{C}=+5 \mathrm{~V} \pm 10 \% ; \mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3, \mathrm{C} 4=10 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=-40$ to $+85^{\circ} \mathrm{C}$ )

| Parameter |  | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Digital Input Voltage Logic Low Logic High | DI1-3 | $\begin{aligned} & \mathrm{V}_{\mathrm{IL}} \\ & \mathrm{~V}_{\mathrm{IH}} \\ & \hline \end{aligned}$ | $\overline{2}$ | - | $0.8$ | V |
| $\begin{array}{r} \text { Input Current } \\ \mathrm{V}_{\mathrm{DI}}=\mathrm{GND} \\ \mathrm{~V}_{\mathrm{DI}}=\mathrm{V}_{\mathrm{CC}} \end{array}$ | DI1-3 | $\begin{aligned} & \mathrm{IIL} \\ & \mathrm{I}_{\mathrm{IH}} \\ & \hline \end{aligned}$ |  | $7$ | $\pm 1.0$ | $\mu \mathrm{A}$ |
| Output High Voltage <br> ( $\mathrm{V}_{\text {DI1-3 }}=$ Logic Low, $\mathrm{R}_{\mathrm{L}}=3 \mathrm{k} \Omega$ ) | $\begin{aligned} & \mathrm{T} \times 1-3 \\ & \mathrm{~T} \times 1-6^{\star} \end{aligned}$ | $\mathrm{V}_{\mathrm{OH}}$ | $\begin{aligned} & 6 \\ & 5 \end{aligned}$ | $\begin{aligned} & 7.5 \\ & 6.5 \end{aligned}$ | - | V |
| Output Low Voltage <br> $\left(\mathrm{V}_{\text {DI1-3 }}=\right.$ Logic High, $\mathrm{R}_{\mathrm{L}}=3 \mathrm{k} \Omega$ ) | $\begin{gathered} \mathrm{T} \times 1-3 \\ \mathrm{~T} \times 1-6^{*} \end{gathered}$ | VOL | $\begin{aligned} & -6 \\ & -5 \end{aligned}$ | $\begin{aligned} & -7.5 \\ & -6.5 \end{aligned}$ | - | V |
| Off Source Impedance | Tx1-3 | $Z_{\text {off }}$ | 300 | - | - | $\Omega$ |
| Output Short Circuit Current (VCC $=5.5 \mathrm{~V}$ ) Tx1-3 Shorted to GND** Tx1-3 Shorted to $\pm 15 \mathrm{~V} * * *$ |  | ISC | - | - | $\begin{gathered} \pm 60 \\ \pm 100 \end{gathered}$ | mA |

* Specifications for a MC14570X powering a MC145406 or MC145403 with three additional drivers/receivers.
** Specification is for one Tx output to be shorted at a time. Should all three driver outputs be shorted simultaneously, device power dissipation limits could be exceeded.
*** This condition could exceed package limitations.
SWITCHING CHARACTERISTICS $\left(\mathrm{V}_{\mathrm{CC}}=+5 \mathrm{~V}, \pm 10 \%\right.$; C1, C2, C3, C4 $=10 \mu \mathrm{~F} ; \mathrm{T}_{\mathrm{A}}=-40$ to $\left.+85^{\circ} \mathrm{C}\right)$

| Parameter |  | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drivers |  |  |  |  |  |  |
| ```Propagation Delay Time Low-to-High ( \(\mathrm{R}_{\mathrm{L}}=3 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}\) or 2500 pF ) High-to-Low ( \(\mathrm{R}_{\mathrm{L}}=3 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}\) or 2500 pF )``` | Tx1-3 | tPLH | - | 0.5 | 1 | $\mu \mathrm{s}$ |
|  |  | tPHL | - | 0.5 | 1 |  |
| Output Slew Rate Minimum Load $\mathrm{R}_{\mathrm{L}}=7 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}=0 \mathrm{pF}$ | Tx1-3 | SR | - | $\pm 6$ | $\pm 30$ | V/4s |
| Maximum Load $\mathrm{R}_{\mathrm{L}}=3 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}=2500 \mathrm{pF}$ |  |  | - | $\pm 5$ | - |  |
| Output Disable Time |  | tDAZ | - | 4 | 10 | $\mu \mathrm{s}$ |
| Output Enable Time |  | tDZA | - | 25 | 50 | ms |

## Receivers

| Propagation Delay Time Low-to-High | DO1-3 | tplH | - | - | 1 | $\mu \mathrm{s}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| High-to-Low |  | ${ }^{\text {tPHL }}$ | - | - | 1 |  |
| Output Rise Time | DO1-3 | $\mathrm{t}_{\mathrm{r}}$ | - | 250 | 400 | ns |
| Output Fall Time | DO1-3 | $t_{f}$ | - | 40 | 100 | ns |
| Output Disable Time |  | traz | - | 4 | 10 | $\mu \mathrm{s}$ |
| Output Enable Time |  | trZA | - | 25 | 50 | ms |

## TRUTH TABLE

Drivers

| DI | TxEN | STB | Tx |
| :---: | :---: | :---: | :---: |
| $X$ | $X$ | $H$ | $Z^{*}$ |
| $X$ | $L$ | $L$ | $L$ |
| $H$ | $H$ | $L$ | $L$ |
| $L$ | $H$ | $L$ | $H$ |

[^0]Receivers

| $\mathbf{R x}$ | STB | DO |
| :---: | :---: | :---: |
| X | H | $\mathrm{Z}^{*}$ |
| $H$ | L | L |
| L | L | H |

## PIN DESCRIPTIONS

## VCC - DIGITAL POWER SUPPLY

This digital supply pin is connected to the logic power supply. This pin should have a $0.33 \mu \mathrm{~F}$ capacitor to ground.

## GND - GROUND

Ground return pin is typically connected to the signal ground pin of the EIA-232D connector (connector pin 7) as well as to the logic power supply ground.

## VDD - POSITIVE POWER SUPPLY

This is the positive output of the on-chip voltage doubler and the positive power supply input of the driver/receiver sections of the device. This pin requires an external storage capacitor to filter the $50 \%$ duty cycle voltage generated by the charge pump.

## VSS - NEGATIVE POWER SUPPLY

This is the negative output of the on-chip voltage doubler/ inverter and the negative power supply input of the driver/ receiver sections of the device. This pin requires an external storage capacitor to filter the $50 \%$ duty cycle voltage generated by the charge pump.

TxEN - OUTPUT ENABLE
This is the driver output enable pin. When this pin is in logic low level, the condition of the driver outputs ( $\mathrm{Tx} 1-3$ ) are in keep OFF (mark) state.

## STB — STAND-BY

The device enters the stand-by mode while this pin is connected to the logic high level. During the stand-by mode, driver and receiver output pins become high-impedance state. In this condition, supply current ICC is below $10 \mu \mathrm{~A}$ (TYP) and can be operated with low current consumption.

## C2+, C2-, C1+, C1- - VOLTAGE DOUBLER AND INVERTER

These are the connections to the internal voltage doubler and inverter, which generate the $\mathrm{V}_{\mathrm{DD}}$ and $\mathrm{V}_{\mathrm{SS}}$ voltages.

## Rx1, Rx2 (Rx3) - RECEIVE DATA INPUT

These are the EIA-232D receive signal inputs. A voltage between +3 and +25 V is decoded as a space, and causes the corresponding DO pin to swing to ground ( 0 V ). A voltage between -3 and -25 V is decoded as a mark, and causes the DO pin to swing up to $V_{\mathrm{CC}}$.

## D01, DO2 (DO3) - DATA OUTPUT

These are the receiver digital output pins, which swing from $\mathrm{V}_{\mathrm{CC}}$ to GND. Each output pin is capable of driving one LSTTL input load.
Output level of these pins is high-impedance while in standby mode.

## DI1, DI2 (DI3) — DATA INPUT

These are the high-impedance digital input pins to the drivers. Input voltage levels on these pins must be between $\mathrm{V}_{\mathrm{CC}}$ and GND.
The level of these input pins are TTL/CMOS compatible.

## Tx1, Tx2 (Tx3) - TRANSMIT DATA OUTPUT

These are the EIA-232D transmit signal output pins, which swing toward $\mathrm{V}_{\mathrm{DD}}$ and $\mathrm{V}_{\text {SS }}$. A logic one at a DI input causes the corresponding Tx output to swing toward VSS. The actual levels and slew rate achieved will depend on the output loading (RL/CL).
The minimum output impedance is $300 \Omega$ when turned off.

## SWITCHING CHARACTERISTICS




## PACKAGE DIMENSIONS

MC145705/06
P SUFFIX
PLASTIC
CASE 738-03

NOTES

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION "L" TO CENTER OF LEAD WHEN FORMED PARALLEL
4. DIMENSION "B" DOES NOT INCLUDE MOLD FLASH.

| DIM | MILLIMETERS |  | INCHES |  |
| :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |
| A | 25.66 | 27.17 | 1.010 | 1.070 |
| B | 6.10 | 6.60 | 0.240 | 0.260 |
| C | 3.81 | 4.57 | 0.150 | 0.180 |
| D | 0.39 | 0.55 | 0.015 | 0.022 |
| E | 1.27 BSC |  | 0.050 BSC |  |
| F | 1.27 | 1.77 | 0.050 | 0.070 |
| G | 2.54 BSC |  | 0.100 BSC |  |
| J | 0.21 | 0.38 | 0.008 | 0.015 |
| K | 2.80 | 3.55 | 0.110 | 0.140 |
| L | 7.62 BSC |  | 0.300 BSC |  |
| M | $0^{\circ}$ | $15^{\circ}$ | $0^{\circ}$ | $15^{\circ}$ |
| N | 0.51 | 1.01 | 0.020 | 0.040 |

NOTES:
DIMENSIONS A AND B ARE DATUMS AND T IS A DATUM SURFACE
2. DIMENSIONING AND TOLERANCING PER ANS Y14.5M, 1982.
3. CONTROLLING DIMENSION: MILLIMETER
4. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
5. MAXIMUM MOLD PROTRUSION $0.15(0.006)$ PER SIDE.

| DIM | MILLIMETERS |  | INCHES |  |
| :---: | ---: | ---: | ---: | ---: |
|  | MIN | MAX | MIN | MAX |
| A | 12.65 | 12.95 | 0.499 | 0.510 |
| B | 7.40 | 7.60 | 0.292 | 0.299 |
| C | 2.35 | 2.65 | 0.093 | 0.104 |
| D | 0.35 | 0.49 | 0.014 | 0.019 |
| F | 0.50 | 0.90 | 0.020 | 0.035 |
| G | 1.27 | BSC | 0.050 |  |
| BSC |  |  |  |  |
| J | 0.25 | 0.32 | 0.010 | 0.012 |
| K | 0.10 | 0.25 | 0.004 | 0.009 |
| M | $0^{\circ}$ | $7^{\circ}$ | $0^{\circ}$ | $7^{\circ}$ |
| P | 10.05 | 10.55 | 0.395 | 0.415 |
| R | 0.25 | 0.75 | 0.010 | 0.029 |



NOTES

1. CHAMFERRED CONTOUR OPTIONAL
2. DIM "L" TO CENTER OF LEADS WHEN FORMED PARAUIEI
3. DIMENSIONS AND TOLERANCES PER ANSI Y14.5M, 1982.
4. CONTROLING DIMENSION: INCH.

| DIM | MILLIMETERS |  | INCHES |  |
| :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |
| A | 31.25 | 32.13 | 1.230 | 1.265 |
| B | 6.35 | 6.85 | 0.250 | 0.270 |
| C | 3.69 | 4.44 | 0.145 | 0.175 |
| D | 0.38 | 0.51 | 0.015 | 0.020 |
| E | 1.27 BSC |  | 0.050 BSC |  |
| F | 1.02 | 1.52 | 0.040 | 0.060 |
| G | 2.54 BSC |  | 0.100 BSC |  |
| J | 0.18 | 0.30 | 0.007 | 0.012 |
| K | 2.80 | 3.55 | 0.110 | 0.140 |
| L | 7.62 BSC |  | 0.300 BSC |  |
| M | $0^{\circ}$ | $15^{\circ}$ | $0^{\circ}$ | $15^{\circ}$ |
| N | 0.51 | 1.01 | 0.020 | 0.040 |

## NOTES:

1. DIMENSIONS A AND B ARE DATUMS AND T IS A DATUM SURFACE.
2. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
3. CONTROLLING DIMENSION: MILLIMETER
4. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
5. MAXIMUM MOLD PROTRUSION $0.15(0.006)$ PER SIDE.

| DIM | MILLIMETERS |  | INCHES |  |
| :---: | ---: | ---: | ---: | ---: |
|  | MIN | MAX | MIN | MAX |
| A | 15.25 | 15.54 | 0.601 | 0.612 |
| B | 7.40 | 7.60 | 0.292 | 0.299 |
| C | 2.35 | 2.65 | 0.093 | 0.104 |
| D | 0.35 | 0.49 | 0.014 | 0.019 |
| F | 0.41 | 0.90 | 0.016 | 0.035 |
| G | 1.27 BSC | 0.050 BSC |  |  |
| J | 0.229 | 0.317 | 0.0090 | 0.0125 |
| K | 0.127 | 0.292 | 0.0050 | 0.0115 |
| M | $0^{\circ}$ | $8^{\circ}$ | $0^{\circ}$ | $8^{\circ}$ |
| P | 10.05 | 10.55 | 0.395 | 0.415 |
| R | 0.25 | 0.75 | 0.010 | 0.029 |

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MOTOROLA


[^0]:    ${ }^{*} \mathrm{~V}_{\mathrm{SS}} \leq \mathrm{V}_{\mathrm{Tx}} \leq \mathrm{V}_{\mathrm{DD}}$

